

1. (12pts) For the matrices A , B and C find the following expressions, if they are defined:
 a) BA b) CB^T c) ACA

$$A = \begin{bmatrix} 3 & 2 \\ 1 & -3 \end{bmatrix}$$

$$B = \begin{bmatrix} 2 & -7 \\ 3 & 0 \\ -1 & 4 \end{bmatrix}$$

$$C = \begin{bmatrix} -2 & 1 \end{bmatrix}$$

$$a) \begin{bmatrix} 2 & -7 \\ 3 & 0 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 1 & -3 \end{bmatrix} = \begin{bmatrix} 6-7 & 4+21 \\ 9+0 & 6+0 \\ -3+4 & -2-12 \end{bmatrix} = \begin{bmatrix} -1 & 25 \\ 9 & 6 \\ 1 & -14 \end{bmatrix}$$

$$b) \begin{bmatrix} -2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 & -1 \\ -7 & 0 & 4 \end{bmatrix} = \begin{bmatrix} -4-7 & -6+0 & 2+4 \end{bmatrix} = \begin{bmatrix} -11 & -6 & 6 \end{bmatrix}$$

$$c) \underbrace{\begin{bmatrix} 3 & 2 \\ 1 & -3 \end{bmatrix}}_{2 \times 2} \underbrace{\begin{bmatrix} -2 & 1 \end{bmatrix}}_{1 \times 2} \begin{bmatrix} 3 & 2 \\ 1 & -3 \end{bmatrix}$$

not defined

2. (20pts) For the matrix A , determine the dimensions of
 a) Row A b) Col A c) Null A d) Null A^T .
 Then give a basis for e) Col A f) Row A g) Null A .

$$A = \begin{bmatrix} 1 & -2 & 0 & 2 \\ -1 & 3 & 1 & -3 \\ 2 & -2 & 3 & 1 \end{bmatrix} \xrightarrow{\substack{R_2+R_1 \\ R_3-2R_1}} \begin{bmatrix} 1 & -2 & 0 & 2 \\ 0 & 1 & 1 & -1 \\ 0 & 2 & 3 & -3 \end{bmatrix} \xrightarrow{R_3-2R_2} \begin{bmatrix} 1 & -2 & 0 & 2 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \xrightarrow{R_2 \cdot (-1)} \begin{bmatrix} 1 & -2 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix} \xrightarrow{R_1+2R_2} \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix} \quad \text{Rank} = 3$$

a) $\dim \text{Row } A = \text{rank } A = 3$ b) $\dim \text{Col } A = \text{rank } A = 3$ c) $\dim \text{Null } A = 4 - \text{rank } A = 1$

d) $\dim \text{null } A^T = 3 - \text{rank } A^T = 3 - \text{rank } A = 0$

e) Col A basis

$$\left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} \right\}$$

f) Row A basis

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

g) Null A basis

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2x_4 \\ 0 \\ x_4 \\ x_4 \end{bmatrix} = x_4 \begin{bmatrix} -2 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

$x_1 = -2x_4$
 $x_2 = 0$
 $x_3 = x_4$

basis for Null $A \rightarrow$

3. (12pts) Below is the augmented matrix of a system of linear equations. Determine the coefficient b for which the system has: a) one solution, b) infinitely many solutions, c) no solutions. (Note: no row operations are needed.)

$$A = \left[\begin{array}{ccc|c} 1 & 3 & 1 & 0 \\ 0 & b^2 - 3b & 0 & b \\ 0 & 0 & b+1 & 4 \end{array} \right]$$

a) one solution if $b^2 - 3b \neq 0$ and $b \neq 0$ and $b+1 \neq 0$
 $b(b-3) = 0 \implies b = 0, 3$ and $b = -1$
 One solution if $b \neq -1, 3$

b) infinitely many solutions $b^2 - 3b = 0$ and $b = 0$
 $b = 0, 3$ and $b = 0$
 if $b = 0$

c) No solution: if $b+1 = 0$ or $(b^2 - 3b = 0$ and $b \neq 0)$
 $b = -1$ or $b = 0, 3$ and $b \neq 0$

No solution if $b = -1$ or $b = 3$

4. (12pts) Let V be the subspace spanned by the vectors below, and \mathbf{u} the additional vector.

a) Show that \mathbf{u} is in V .

b) Determine a basis for V that consists of \mathbf{u} , the first vector in the set S , and possibly additional vectors from the set. (You do not need to do a lot more after a). If \mathbf{u} can be written as a linear combination of some vectors from the set — and a) easily gives you the coefficients — then some vector from the set can be easily written as a linear combination of \mathbf{u} and other vectors from the set.)

$$S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ 0 \\ -3 \end{bmatrix} \right\} \quad \mathbf{u} = \begin{bmatrix} 9 \\ -3 \\ 2 \\ -7 \end{bmatrix}$$

$$a) \begin{bmatrix} 1 & -1 & 1 & 3 & 9 \\ 0 & 1 & -1 & -1 & -3 \\ 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & -3 & -7 \end{bmatrix} \xrightarrow{R_1 - R_3} \begin{bmatrix} 0 & -1 & 0 & 3 & 7 \\ 0 & 1 & -1 & -1 & -3 \\ 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & -3 & -7 \end{bmatrix} \xrightarrow{R_1 + R_2} \begin{bmatrix} 0 & 0 & -1 & 2 & 4 \\ 0 & 1 & -1 & -1 & -3 \\ 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & -3 & -7 \end{bmatrix} \xrightarrow{R_1 \cdot (-1)} \begin{bmatrix} 0 & 0 & 1 & -2 & -4 \\ 0 & 1 & -1 & -1 & -3 \\ 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & -3 & -7 \end{bmatrix} \xrightarrow{R_2 + R_1} \begin{bmatrix} 0 & 0 & 1 & -2 & -4 \\ 0 & 1 & 0 & -1 & -1 \\ 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & -3 & -7 \end{bmatrix} \xrightarrow{R_2 - R_4} \begin{bmatrix} 0 & 0 & 1 & -2 & -4 \\ 0 & 0 & 0 & 2 & 6 \\ 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & -3 & -7 \end{bmatrix}$$

$\dim V = 3$, First three vectors are a basis and $\mathbf{u} \in V$ because the system

$A\vec{x} = \vec{u}$ has a solution

$$b) \begin{bmatrix} 1 & -1 & 0 & 5 & 13 \\ 0 & 1 & 0 & -3 & -9 \\ 0 & 0 & 1 & -2 & -4 \end{bmatrix} \vec{x} \sim \begin{bmatrix} 1 & 0 & 0 & 2 & 6 \\ 0 & 1 & 0 & -3 & -9 \\ 0 & 0 & 1 & -2 & -4 \end{bmatrix}$$

It follows that

$$\vec{u} = 6\vec{u}_1 - 7\vec{u}_2 - 4\vec{u}_3$$

$$\text{So } \vec{u}_3 = \frac{1}{4}(-\vec{u} + 6\vec{u}_1 - 7\vec{u}_2)$$

Since \vec{u}_3 is a lin. comb. of $\vec{u}_1, \vec{u}_2, \vec{u}$.

$$\text{Thus, } V = \text{span} \{ \vec{u}_1, \vec{u}_2, \vec{u}_3 \} = \text{span} \{ \vec{u}_1, \vec{u}_2, \vec{u} \} = \text{span} \{ \vec{u}_1, \vec{u}_2, \vec{u} \}$$

Since $\dim V = 3$ it follows that $\{ \vec{u}_1, \vec{u}_2, \vec{u} \}$ are lin. indep., hence a basis for V

5. (12pts) Matrix A is given below.

a) Evaluate its determinant by any (efficient) method.

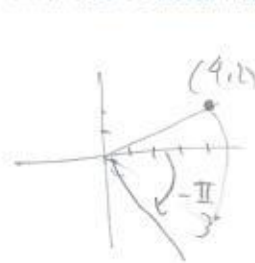
b) State if A is invertible and justify.

$$\begin{vmatrix} 0 & 4 & -1 & 1 \\ -3 & 1 & 1 & 2 \\ 1 & 0 & -2 & 3 \\ 2 & 3 & 0 & 1 \end{vmatrix} \xrightarrow{\substack{R_1 \leftrightarrow R_3 \\ R_2 \leftrightarrow R_4}} \begin{vmatrix} 1 & 0 & -2 & 3 \\ 0 & 3 & 4 & -5 \\ 0 & 4 & -1 & 1 \\ 0 & 1 & -5 & 11 \end{vmatrix} = (-1)^{3+1} \cdot 1 \begin{vmatrix} 4 & -1 & 1 \\ 1 & -5 & 11 \\ 3 & 4 & -5 \end{vmatrix} \xrightarrow{\substack{\cdot (-1) \\ 2 \cdot (-3)}} \begin{vmatrix} 4 & -1 & 1 \\ 1 & -5 & 11 \\ 3 & 4 & -5 \end{vmatrix}$$

$$= \begin{vmatrix} 0 & 19 & -43 \\ 1 & -5 & 11 \\ 0 & 19 & -38 \end{vmatrix} = (-1)^{2+1} (19 \cdot (-38) - 19 \cdot (-43)) = -19(-38 + 43) = -19 \cdot 5 = -95$$

b) Since $\det A \neq 0$, the matrix is invertible

6. (6pts) Write the rotation matrix for a clockwise rotation around the origin by angle $\frac{\pi}{3}$ and use it find where the point $(4, 2)$ lands after it is rotated.



$$R = \begin{bmatrix} \cos(-\frac{\pi}{3}) & -\sin(-\frac{\pi}{3}) \\ \sin(-\frac{\pi}{3}) & \cos(-\frac{\pi}{3}) \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

$$\begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 4 \\ 2 \end{bmatrix} = \begin{bmatrix} \frac{4}{2} + \frac{2\sqrt{3}}{2} \\ \frac{-4\sqrt{3} + 2}{2} \end{bmatrix} = \begin{bmatrix} \frac{4+2\sqrt{3}}{2} \\ \frac{-4\sqrt{3}+2}{2} \end{bmatrix} = \begin{bmatrix} 2+\sqrt{3} \\ 1-2\sqrt{3} \end{bmatrix}$$

7. (14pts) The matrix A is given below.

a) Find the inverse of A .

b) Use the inverse to easily solve the system below.

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 3 & 4 & 1 \\ -1 & 4 & 4 \end{bmatrix} \xrightarrow{\substack{+3R_1 \\ -1R_2}} \begin{bmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 3 & 4 & 1 & | & 0 & 1 & 0 \\ -1 & 4 & 4 & | & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -3 & 1 & 0 \\ 0 & 5 & 4 & | & 1 & 0 & 1 \end{bmatrix} \xrightarrow{\cdot (-5)} \begin{bmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -3 & 1 & 0 \\ 0 & 0 & -1 & | & 16 & -5 & 1 \end{bmatrix}$$

$$\begin{aligned} x_1 + x_2 &= 7 \\ 3x_1 + 4x_2 + x_3 &= 3 \\ -x_1 + 4x_2 + 4x_3 &= -5 \end{aligned}$$

$$\sim \begin{bmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -3 & 1 & 0 \\ 0 & 0 & 1 & | & -16 & 5 & -1 \end{bmatrix} \xrightarrow{\substack{+R_3 \\ \cdot (-1)}} \begin{bmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -3 & 1 & 0 \\ 0 & 0 & 1 & | & 16 & -5 & 1 \end{bmatrix} \xrightarrow{\cdot (-1)} \begin{bmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -3 & 1 & 0 \\ 0 & 0 & 1 & | & -16 & 5 & -1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & | & -12 & 4 & -1 \\ 0 & 1 & 0 & | & -13 & -4 & 1 \\ 0 & 0 & 1 & | & -16 & 5 & -1 \end{bmatrix} \quad \vec{A} = \begin{bmatrix} -12 & 4 & -1 \\ 13 & -4 & 1 \\ -16 & 5 & -1 \end{bmatrix}$$

Sol. to $A\vec{x} = \vec{b}$
is $\vec{A}^{-1}\vec{b}$ if A is invertible

$$\vec{x} = \begin{bmatrix} -12 & 4 & -1 \\ 13 & -4 & 1 \\ -16 & 5 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ 3 \\ -5 \end{bmatrix} = \begin{bmatrix} -84 + 12 + 5 \\ 91 - 12 + 5 \\ -112 + 15 + 5 \end{bmatrix} = \begin{bmatrix} -67 \\ 74 \\ -92 \end{bmatrix}$$

8. (10pts) Find the standard matrix of the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ and determine whether T is a) one-to-one, or b) onto.

$$T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} 2x_1 + 3x_2 - 7x_3 \\ x_1 - 3x_2 + 3x_3 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 3 & -7 \\ 1 & -3 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 & 3 \\ 2 & 3 & -7 \end{bmatrix} \xrightarrow{\cdot(-1)} \begin{bmatrix} 1 & -3 & 3 \\ 0 & 9 & -13 \end{bmatrix} \leftarrow \text{rank} = 2$$

a) nullity $A = 3 - \text{rank } A = 1$ since nullity $A \neq 0$, T is not one-to-one
 b) since $\text{rank } A = \dim \mathbb{R}^2$, T is onto

9. (12pts) The set W is defined below.

a) Use the definition to show W is a subspace of \mathbb{R}^3 .
 b) Give a basis for W .

$$W = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid 3x_1 + 2x_2 + x_3 = 0 \right\}$$

$$\begin{aligned} \text{b) } 3x_1 &= -2x_2 - x_3 \\ x_1 &= -\frac{2}{3}x_2 - \frac{1}{3}x_3 \\ x_2, x_3 &\text{ free} \end{aligned}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -\frac{2}{3}x_2 - \frac{1}{3}x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -\frac{2}{3} \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix}$$

basis for W .

$$\text{Let } \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}, \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \in W$$

$$\begin{aligned} \text{Then } 3u_1 + 2u_2 + u_3 &= 0 \\ 3v_1 + 2v_2 + v_3 &= 0 \end{aligned}$$

$$3u_1 + 3v_1 + 2u_2 + 2v_2 + u_3 + v_3 = 0$$

$$3(u_1 + v_1) + 2(u_2 + v_2) + (u_3 + v_3) = 0$$

so $\begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{bmatrix}$ satisfies the equation so it is in W

$$c \cdot 3u_1 + c \cdot 2u_2 + c \cdot u_3 = 0$$

$$3(cu_1) + 2(cu_2) + cu_3 = 0$$

$\begin{bmatrix} cu_1 \\ cu_2 \\ cu_3 \end{bmatrix} = c \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$ satisfies the equation so it is in W

W is a subspace.

10. (24pts) Are the following statements true or false? Justify your answer by giving a logical argument or a counterexample.

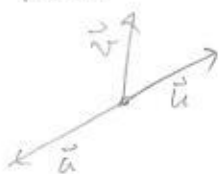
a) If \mathbf{a} is in $\text{Span}\{\mathbf{u}, \mathbf{v}\}$, then \mathbf{v} is in $\text{Span}\{\mathbf{u}, \mathbf{a}\}$.

b) If $\mathbf{w} \in \text{Span}\{\mathbf{u}, \mathbf{v}\}$ and T is a linear transformation, then $T(\mathbf{w}) \in \text{Span}\{T(\mathbf{u}), T(\mathbf{v})\}$

c) For a 3×4 matrix A , its associated linear transformation T_A is not one-to-one.

d) If \mathbf{u} and \mathbf{v} are eigenvectors for a matrix A , then $\mathbf{u} + \mathbf{v}$ is an eigenvector for A .

a) False



$$\vec{a} = -2\vec{u} \text{ so } \vec{a} \in \text{Span}\{\vec{u}, \vec{v}\}$$

$$\text{but } \vec{v} \notin \text{Span}\{\vec{u}, \vec{a}\}$$

$$\vec{u} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \vec{a} = \begin{bmatrix} -2 \\ 0 \end{bmatrix} \quad \vec{v} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ is not in } \text{Span}\left\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \end{bmatrix}\right\}$$

b) True If $\vec{w} \in \text{Span}\{\vec{u}, \vec{v}\}$ $\vec{w} = a\vec{u} + b\vec{v}$ so $T(\vec{w}) = T(a\vec{u} + b\vec{v})$
 $= T(a\vec{u}) + T(b\vec{v}) = aT(\vec{u}) + bT(\vec{v})$ so $T(\vec{w}) \in \text{Span}\{T(\vec{u}), T(\vec{v})\}$

c) True: nullity $A = 4 - \text{rank } A$. Since $\text{rank } A \leq 3$, $4 - \text{rank } A \geq 1 > 0$
 Hence, nullity $A \neq 0$, so T_A is not one-to-one

d) False. Let $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ Then \vec{e}_1 is an eigenvector for $\lambda = 1$
 \vec{e}_2 is an eigenvector for $\lambda = 0$
 $A(\vec{e}_1 + \vec{e}_2) = \vec{e}_1 + \vec{0} = \vec{e}_1$, not a multiple of $\vec{e}_1 + \vec{e}_2$.

11. (16pts) The matrix A is given below.

a) Find the eigenvalues for the matrix.

b) For each eigenvalue, find the basis of the corresponding eigenspace.

$$A = \begin{bmatrix} 6 & 0 & 0 \\ -2 & 3 & 5 \\ 1 & 3 & 1 \end{bmatrix} \quad \det(A - \lambda I) = \begin{vmatrix} 6-\lambda & 0 & 0 \\ -2 & 3-\lambda & 5 \\ 1 & 3 & 1-\lambda \end{vmatrix} = (6-\lambda) \begin{vmatrix} 3-\lambda & 5 \\ 3 & 1-\lambda \end{vmatrix}$$

$$= (6-\lambda) \left((3-\lambda)(1-\lambda) - 15 \right) = (6-\lambda) (\lambda^2 - 4\lambda + 3 - 15)$$

We see the eigenvalues
are $\lambda = 6, -2$

$$\begin{aligned} &= -(\lambda-6)(\lambda^2 - 4\lambda - 12) \\ &= -(\lambda-6)(\lambda-6)(\lambda+2) = -(\lambda-6)^2(\lambda+2) \end{aligned}$$

Eigenspace of $\lambda = 6$

$$A - 6I = \begin{bmatrix} 0 & 0 & 0 \\ -2 & -3 & 5 \\ 1 & 3 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & -5 \\ 0 & 3 & -5 \\ 0 & 3 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & -5 \\ 0 & 1 & -\frac{5}{3} \end{bmatrix}$$

$$x_1 = 0 \quad x_2 = \frac{5}{3}x_3 \quad x_3 \text{ free} \quad \text{Basis} = \left\{ \begin{bmatrix} 0 \\ \frac{5}{3} \\ 1 \end{bmatrix} \right\}$$

Eigenspace for $\lambda = -2$

$$A + 2I = \begin{bmatrix} 8 & 0 & 0 \\ -2 & 5 & 5 \\ 1 & 3 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 5 & 5 \\ 0 & 3 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$x_1 = 0 \quad x_2 = -x_3 \quad \text{Basis} = \left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\}$$

Bonus. (10pts) Find the eigenvalues of the matrix. Brute force will probably work poorly: use some row or column operations, as well as factoring out a common factor in a row or column.

$$A = \begin{bmatrix} -1 & 4 & -4 & -4 \\ 5 & -2 & 1 & 6 \\ 0 & 0 & -1 & 0 \\ 5 & -5 & 5 & 9 \end{bmatrix} \quad \begin{vmatrix} -1-\lambda & 4 & -4 & -4 \\ 5 & -2-\lambda & 1 & 6 \\ 0 & 0 & -1-\lambda & 0 \\ 5 & -5 & 5 & 9-\lambda \end{vmatrix} = (-1-\lambda) \begin{vmatrix} -1-\lambda & 4 & -4 \\ 5 & -2-\lambda & 6 \\ 5 & -5 & 9-\lambda \end{vmatrix} \quad \text{Eigenvalues: } \lambda = -1, 3, 4$$

$$= (-1-\lambda) \begin{vmatrix} -1-\lambda & 3-\lambda & -4 \\ 5 & 3-\lambda & 6 \\ 5 & 0 & 9-\lambda \end{vmatrix} = (-1-\lambda)(3-\lambda) \begin{vmatrix} -1-\lambda & 1 & -4 \\ 5 & 1 & 6 \\ 5 & 0 & 9-\lambda \end{vmatrix} \stackrel{(-)}{=} (\lambda+1)(\lambda-3) \begin{vmatrix} -6-\lambda & 0 & -10 \\ 5 & 1 & 6 \\ 5 & 0 & 9-\lambda \end{vmatrix}$$

$$= (\lambda+1)(\lambda-3) \begin{vmatrix} -6-\lambda & -10 \\ 5 & 9-\lambda \end{vmatrix} = (\lambda+1)(\lambda-3) \left((-6-\lambda)(9-\lambda) + 50 \right) = (\lambda+1)(\lambda-3) (\lambda^2 - 3\lambda - 54 + 50)$$

$$= (\lambda+1)(\lambda-3) (\lambda^2 - 3\lambda - 4) = (\lambda+1)(\lambda-3)(\lambda-4)(\lambda+1)$$

$$= (\lambda+1)^2(\lambda-3)(\lambda-4)$$