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Note Title

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Example

Consider the Hilbert

$$H_3 = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \end{bmatrix}$$

which is ill-conditioned.

Now

$$H_3^{-1} = \begin{bmatrix} 9 & -36 & 30 \\ -36 & 192 & -180 \\ 30 & -180 & 180 \end{bmatrix}$$

$$\|H_3\|_1 = \|H_3\|_\infty = \frac{11}{6}$$

$$\|H_3^{-1}\|_1 = \|H_3^{-1}\|_\infty = 408$$

Condition number

$$\begin{aligned} K_1(H_3) &= \|H_3\|_1 \cdot \|H_3^{-1}\|_1 \\ &= \frac{11}{6} (408) \end{aligned}$$

$$= 748 \quad \begin{matrix} \nearrow \\ \text{LARGE} \end{matrix} \quad A \text{ is ill-conditioned}$$

Note

$$K_\infty(H_3) = 748$$

For n as large as 6, the ill-conditioning is extremely bad with

$$k_1(H_6) = k_\infty(H_6) \approx 29 \times 10^6$$

Basic Iterative Methods

We are still considering the problem of solving n nonsingular equations in n unknowns.

$$Ax = b$$

Suppose that Q and F are $n \times n$ matrices such that $A = Q - F$

Then with the splitting of A , the problem may be written as

$$(Q-F)x = b$$

i.e.

$$Qx = Fx + b$$

Note that $F = Q - A$

So

$$Qx = (Q - A)x + b$$

Algorithm:

- we select a non singular matrix Q
- Choose an arbitrary ^{starting} vector $x^{(0)}$
- Generate a sequence $x^{(1)}, x^{(2)}, \dots$ recursively from the equation

$$(*) \quad Qx^{(k+1)} = (Q-A)x^{(k-1)} + b \quad k=1, 2, 3, \dots$$

In principle, the numerical procedure is designed so that the sequence of vectors converge to the actual solution.

Question How does one choose the non singular matrix Q ?

- System $(*)$ should be easy to solve for $x^{(k)}$ for known right hand side.

Coefficient matrix Q being diagonal, block diagonal, banded, lower triangular and upper triangular would be nice!

$$2x_1 - x_2 = 3$$

$$x_2 = 5$$

$$\begin{bmatrix} 2 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

- matrix Q should be chosen to ensure that the sequence $x^{(k)}$ converges irrespective of the initial vector used. (Rapid convergence ideally)

Jacobi Method

The system $Ax = b$ written in a more detailed

form is

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{i1}x_1 + a_{i2}x_2 + \dots + a_{in}x_n = b_i$$

$$\vdots$$

$$a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n$$

For the i th equation we solve for the i th unknown term. (Assume that all diagonal elements are non zero. Can usually rearrange if not so!)

$$a_{11}x_1 = - (a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n) + b_1$$

$$a_{22}x_2 = - (a_{21}x_1 + a_{23}x_3 + \dots + a_{2n}x_n) + b_2$$

\vdots

$$a_{ii}x_i = - (a_{i1}x_1 + a_{i2}x_2 + \dots + a_{i,i-1}x_{i-1} + a_{i,i+1}x_{i+1} + \dots$$

\vdots

$$+ a_{in}x_n) + b_i$$

$$a_{nn}x_n = - (a_{n1}x_1 + a_{n2}x_2 + \dots + a_{n,n-1}x_{n-1}) + b_n$$

$$\text{i.e. } x_1 = -\frac{1}{a_{11}} (a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n) + \frac{b_1}{a_{11}}$$

$$x_2 = -\frac{1}{a_{22}} (a_{21}x_1 + a_{23}x_3 + \dots + a_{2n}x_n) + \frac{b_2}{a_{22}}$$

⋮

$$x_i = -\frac{1}{a_{ii}} (a_{i1}x_1 + a_{i2}x_2 + \dots + a_{i,i-1}x_{i-1} + a_{i,i+1}x_{i+1} + \dots + a_{in}x_n) + \frac{b_i}{a_{ii}}$$

$$x_n = -\frac{1}{a_{nn}} (a_{n1}x_1 + \dots + a_{n,n-1}x_{n-1}) + \frac{b_n}{a_{nn}}$$

Compact form:

$$x_i = -\sum_{j=2}^n \frac{a_{ij}}{a_{ii}} x_j + \frac{b_i}{a_{ii}}$$

$$x_2 = - \sum_{j=1}^n \frac{a_{2j}}{a_{22}} x_j + \frac{b_2}{a_{22}}$$

$$\vdots$$

$$x_i = - \sum_{j=1}^n \frac{a_{ij}}{a_{ii}} x_j + \frac{b_i}{a_{ii}}$$

$$\vdots$$

$$x_n = - \sum_{j=1}^{n-1} \frac{a_{nj}}{a_{nn}} x_j + \frac{b_n}{a_{nn}}$$

The Jacobi method is

$$x_1^{(k)} = - \sum_{j=2}^n \frac{a_{1j}}{a_{11}} x_j^{(k-1)} + \frac{b_1}{a_{11}}$$

$$x_2^{(k)} = - \sum_{j=1}^n \frac{a_{2j}}{a_{22}} x_j^{(k-1)} + \frac{b_2}{a_{22}}$$

⋮
⋮

$$x_i^{(k)} = - \sum_{j=1}^n \frac{a_{ij}}{a_{ii}} x_j^{(k-1)} + \frac{b_i}{a_{ii}}$$

⋮
⋮

$$x_n^{(k)} = - \sum_{j=1}^{n-1} \frac{a_{nj}}{a_{nn}} x_j^{(k-1)} + \frac{b_n}{a_{nn}}$$